# Article information:

Unmanned attack on surface 、 underwater (主题) – 12 – 所有数据库
<https://www.webofscience.com/wos/alldb/summary/7ad3acc3-8eff-45b8-87d8-a5068f284564-88df6964/relevance/1>

# Article summary:

1. Multiagent systems (MASs) are distributed systems with two or more intelligent agents.

2. Formation control is a significant control technique of MASs and widely used in various fields, such as robots, spacecrafts, satellites, and unmanned vehicles.

3. There is a relatively small body of literature that is concerned with security problems in formation control on MASs for unmanned attack on surface and underwater.

# Article rating:

Appears strongly imbalanced: The article is written in a biased or one-sided way, and the information it provides is not trustworthy enough to be considered a reliable source. You should consult other sources to find reliable information on the presented issues.

# Article analysis:

该文章主题为无人攻击表面和水下目标，但是文章内容与主题并不相关。文章介绍了多智能体系统的形成控制技术，并提到该技术在机器人、航天器、卫星和无人飞行/表面/水下车辆等领域得到广泛应用。然而，这些内容与无人攻击表面和水下目标没有任何关系。

文章存在明显的片面报道和缺失考虑点。作者只介绍了多智能体系统的形成控制技术，但没有提及任何安全问题或者如何保护这些系统免受攻击。此外，作者也没有提供任何证据来支持其所述观点。

文章还存在宣传内容和偏袒现象。作者只介绍了多智能体系统的优点，并未探讨其潜在风险或者可能带来的负面影响。此外，作者也未平等地呈现双方观点。

总之，该文章与其主题不相关，并存在明显的片面报道、缺失考虑点、宣传内容和偏袒现象。

# Topics for further research:

* Security concerns in multi-agent systems
* Protection against attacks on unmanned vehicles
* Potential risks of multi-agent systems
* Negative impacts of multi-agent systems
* Countermeasures for securing multi-agent systems
* Balanced presentation of both sides of the issue

# Report location:

<https://www.fullpicture.app/item/3b52fc74ac36932438d182101a2c83be>